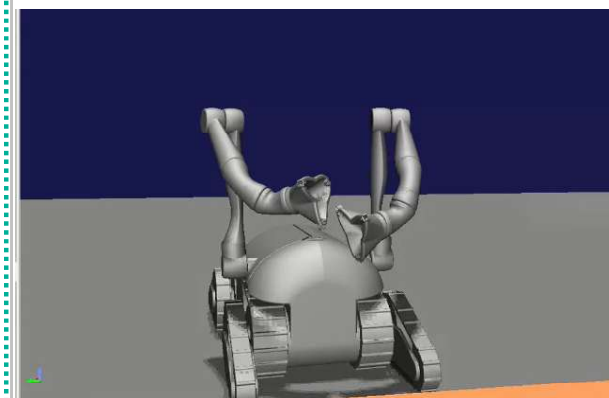


## Key Development Points

This insect-inspired crawler robot can adapt to a variety of environments. Its three-fingered arm allows it to perform complex tasks and delicate work. Its unique design,



## Team Introduction

This team was formed to achieve results with robotics technology using ROS2. Through the simulator, we aim to gain an in-depth understanding of the physical behavior of

Currently, we are focusing on topic communication, but in the future, we would like to introduce service communication a



| Role        | Name            | Affiliation/Position     | Areas of expertise, research fields |
|-------------|-----------------|--------------------------|-------------------------------------|
| team leader | Takeuchi Toraji | Spes Tech LLC / engineer | Robot development using ROS2        |

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