Simulation Disaster

Challenge

REL-UoA

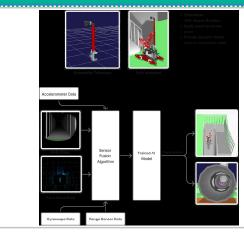
Japan, University of Aizu





Key Development Points

We developed intelligent robots: a slope-adaptive crawler with 360° camera and LiDAR for safe terrain inspection, and an AI drone with multi-sensor fusion for autonomous



We are a robotics team aiming to create robots for hazardous tasks. By collaborating and innovating, we grow our skills, compete globally, and advance technology.



Introduction We develop adaptable robots with AI and sensors to ease workload, improve safety, and advance robotics.



Role	Name	Affiliation/Position	Areas of expertise, research fields
Team Reader	Jura TAKAMOTO	University of Aizu, Naruse Labo, Grade 4th	Research on Robot Arm

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