



Key Development Points

We have mounted a gripper with infinitely rotatable wrists, manufactured from PA12CF, onto a 6-degree-of-freedom manipulator.



Team Introduction

We are engaged in the research and development of disaster rescue robots at the Yamazaki Laboratory at Meisei University.

We are focusing our efforts on realizing and commercializing innovative mechanisms.



| Role | Name | Affiliation/Position | Areas of expertise, research fields |
|-------------|------------|------------------------------------|-------------------------------------|
| Team leader | Jaefun Seo | Meisei University / Docter Student | Rescue Robot |

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Websites, etc. <https://www.sae.meisei-u.ac.jp/course/mechanics/>